

Cap 3

1)



A qtd de linhas de força que saem de $2q$ em direção a $-q$ é a dobra do saldo de $-q$, já que a magnitude tem a dobra

2)

i) $\vec{E} = \vec{E}_1 + \vec{E}_2$

$\vec{E} = 2|\vec{E}_1| \cos \theta \hat{p}$

$\vec{E} = 2 \frac{1}{4\pi\epsilon_0} \frac{e}{a^2+p^2} \cdot \frac{p}{(a^2+p^2)^{3/2}} \hat{p}$

$\vec{E} = \frac{ep}{2\pi\epsilon_0(a^2+p^2)^{3/2}} \hat{p}$

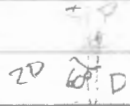
ii)

$m\omega^2 p = -e\vec{E} = -\frac{e^2 p}{2\pi\epsilon_0(a^2+p^2)^{3/2}}$

$\omega^2 = -\frac{e^2}{2\pi m \epsilon_0(a^2+p^2)^{3/2}}$

$E \cdot 2\pi r^2 = \frac{qF^2 0}{\epsilon_0}$

3)



$dE = k dQ = \frac{k \sigma dx dy}{D^2+x^2+y^2}$

$E = k\sigma \int_{-D/2}^{D/2} \int_{-a/2}^{a/2} \frac{dx dy}{(D^2+x^2+y^2)^{3/2}}$

$DQ = \sigma dx dy$

$D = \int_0^{\pi/2} \sec^2 \phi d\phi$

$D^2 = \sec^2 \phi$

$D = \sec \phi$

$du = -\sin \phi d\phi$

$E_x = 2\pi k \sigma \int_0^{\pi/2} \sin \phi d\phi = -\frac{2\sigma}{2\epsilon_0} \cos \phi \Big|_0^{\pi/2} = \frac{\sigma}{\epsilon_0}$

$\frac{E_x}{E} = \frac{1}{2}$ cgd

4) $\lambda = \frac{Q}{l}$ a)

$Q = \lambda l$
 $\lambda = \frac{dQ}{dl}$



$d\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{dQ}{r^2} \hat{x} = \frac{\lambda dl}{4\pi\epsilon_0 r^2} \hat{x}$

$\vec{E} = \frac{\lambda}{4\pi\epsilon_0} \int_d^{d+l} \frac{dl}{r^2} \hat{x}$

$\vec{E} = -\frac{\lambda}{4\pi\epsilon_0} \left[\frac{1}{r} \right]_d^{d+l} \hat{x}$

$\vec{E} = \frac{\lambda}{4\pi\epsilon_0} \left(\frac{1}{d} - \frac{1}{d+l} \right) \hat{x} = \frac{\lambda l}{4\pi\epsilon_0 d(d+l)} \hat{x}$

b) $E = \frac{9 \cdot 10^9 \cdot 3 \cdot 10^{-6}}{5 \cdot 10^{-2} \cdot 10 \cdot 10^{-2}} = 5,4 \cdot 10^8 \text{ N/C}$

5) $d\vec{E} = -\frac{2dQk}{\left(\frac{b}{2}\right)^2 + x^2} \cos\theta \hat{z} = -\frac{2k\lambda dx}{\left(\frac{b}{2}\right)^2 + x^2} \cos\theta \hat{z}$

$\lambda = \frac{dQ}{dx}$
 $\frac{x}{b} = \tan\theta$
 $\frac{b}{2} = \frac{b}{2} + x \tan\theta$
 $dx = \frac{b}{2} \sec^2\theta d\theta$
 $x = \text{arctg} \frac{a}{b}$

$\vec{E} = -\int_{-\text{arcsen} \frac{a}{\sqrt{a^2+b^2}}}^{\text{arcsen} \frac{a}{\sqrt{a^2+b^2}}} \frac{4k\lambda \cos\theta d\theta}{b} \hat{z}$

$\vec{E} = -\frac{8k\lambda a}{b\sqrt{a^2+b^2}} \hat{z} = -\frac{2\lambda a}{\pi\epsilon_0 b\sqrt{a^2+b^2}} \hat{z}$

resp. mais

c) Pela simetria: $|E_x| = |E_y| = E$

$E_z \rightarrow$ Será calculado apenas para um lado e seu módulo multiplicado por 4, já q o sentido é o msm

$\lambda = \frac{dQ}{dx}$
 $dE = \frac{dQ \cos\theta}{4\pi\epsilon_0(D^2+l^2+x^2)^{3/2}} = \frac{\lambda dx \cdot D}{\pi\epsilon_0(D^2+l^2+x^2)^{3/2}} = \frac{\lambda D \sqrt{D^2+l^2} \sec^2\phi d\phi}{\pi\epsilon_0(D^2+l^2)^{3/2} \cos\phi}$

$\lambda = \frac{Q}{l}$
 $x = \sqrt{D^2+l^2} \tan\phi$
 $dx = \sqrt{D^2+l^2} \sec^2\phi d\phi$

$l \Rightarrow \cos\phi = \frac{l}{\sqrt{D^2+l^2}}$
 $\cos\phi = \frac{l}{\sqrt{D^2+l^2}}$
 $\sin\phi = \frac{D}{\sqrt{D^2+l^2}}$

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7) ~~$\phi_e = \frac{q_{int}}{\epsilon_0}$~~

a) $\phi_e = \frac{q}{6\epsilon_0}$

b) $\phi_e = \frac{q}{24\epsilon_0}$ (opostas)

$\phi_e = 0$ (adjacentes)

8) $E_1 = 300 \text{ N/C}$

$\vec{E}_1 = -300 \hat{z} \text{ N/C}$

$h = 1400 \text{ m} \Rightarrow E = 20 \hat{z} \text{ N/C}$

$\rho = \frac{q}{V} = ?$

$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$

$280 = \frac{\rho \cdot 1400}{\epsilon_0}$

$\rho = \frac{\epsilon_0}{S}$

$\rho = \frac{1}{20 \text{ m}} = 1,8 \cdot 10^{-12} \text{ C/m}^3$

a) $\vec{E}_1 \uparrow \quad \sigma \cdot \sqrt{\vec{E}_2}$

$|\vec{E}_1| = |\vec{E}_2|$

$\vec{E}_1 \downarrow \quad \sqrt{\vec{E}_2}$

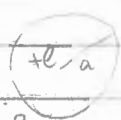
$\Rightarrow \vec{E}_{acima} = 0$

2 $\vec{E}_1 \downarrow \quad \sigma \cdot \sqrt{\vec{E}_2}$

$\Rightarrow \vec{E}_{entre} = -2 \cdot \frac{\sigma}{2\epsilon_0} = -\frac{\sigma}{\epsilon_0}$

$\Rightarrow \vec{E}_{abaixo} = 0$

10)



a)



$\oint \vec{E} \cdot d\vec{S} = \frac{q_{int}}{\epsilon_0} = \frac{e}{\epsilon_0}$

$a = 1 \text{ \AA}$

$E \cdot \oint dS = \frac{e r^3}{4\pi \epsilon_0} = E \cdot 4\pi r^2$

$\vec{E} = \frac{e \vec{r}}{4\pi \epsilon_0 a^3}$

b) $F = -eE = -\frac{e^2 r}{4\pi \epsilon_0 a^3} \Rightarrow MHS \quad \mu \pi r^2 = \frac{e}{\omega^2}$

c) $\omega^2 = \frac{e^2}{4\pi \epsilon_0 a^3 m}$

$\omega = \frac{e}{2a \sqrt{\pi \epsilon_0 a m}}$

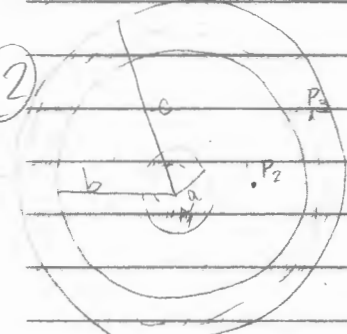
$\omega = \frac{e}{4\pi a \sqrt{\pi \epsilon_0 a m}} = 3,5 \cdot 10^{15} \text{ Hz}$

11) $\text{div}(c \cdot r) =$

$$\text{div}(c \cdot r) = \frac{\partial}{\partial x}(c_1 r_x) + \frac{\partial}{\partial y}(c_2 r_y) + \frac{\partial}{\partial z}(c_3 r_z)$$

$$= c_1 \frac{\partial}{\partial x}(x) + c_2 \frac{\partial}{\partial y}(y) + c_3 \frac{\partial}{\partial z}(z) = c_1 + c_2 + c_3$$

12)



a) $\oint_S \vec{E} \cdot \hat{n} dS = \frac{q_{\text{int}}}{\epsilon_0}$

$$E \cdot 4\pi r^2 = \frac{\rho \frac{4}{3}\pi r^3}{\epsilon_0}$$

$$\vec{E} = \frac{\rho r}{3\epsilon_0} \hat{r}$$

b) $E \cdot 4\pi r^2 = \frac{\rho \frac{4}{3}\pi a^3}{\epsilon_0} \Rightarrow \vec{E} = \frac{\rho a^3}{3\epsilon_0 r^2} \hat{r}$

c) $E \cdot 4\pi r^2 = \frac{\rho \left(\frac{4}{3}\pi a^3 + \frac{4}{3}\pi r^3 - \frac{4}{3}\pi b^3 \right)}{\epsilon_0}$

$$\vec{E} = \frac{\rho (a^3 - b^3 + r^3)}{3\epsilon_0 r^2} \hat{r}$$

d) $E \cdot 4\pi r^2 = \frac{\rho \left(\frac{4}{3}\pi a^3 + \frac{4}{3}\pi b^3 - \frac{4}{3}\pi c^3 \right)}{\epsilon_0}$

$$\vec{E} = \frac{\rho (a^3 - b^3 + c^3)}{3\epsilon_0 r^2} \hat{r}$$

13) $\rho(r) = \rho_0 e^{-\frac{r}{a}}$

a) $dQ = \rho(r) dV = \rho_0 e^{-\frac{r}{a}} (r d\theta \cdot r \sin\theta d\varphi \cdot dr)$

$$Q = \int_0^\infty \int_0^\pi \int_0^{2\pi} \rho_0 e^{-\frac{r}{a}} \sin\theta d\theta d\varphi dr = 2\pi \rho_0 \int_0^\infty r^2 e^{-\frac{r}{a}} \sin\theta d\theta dr = 4\pi \rho_0 \int_0^\infty r^2 e^{-\frac{r}{a}} dr$$

$$= 4\pi \rho_0 \left(a r^2 e^{-\frac{r}{a}} + \int_0^\infty 2 r a e^{-\frac{r}{a}} dr \right) = 4\pi \rho_0 \left(r^2 a e^{-\frac{r}{a}} + 2a \left(a r e^{-\frac{r}{a}} + \int_0^\infty a e^{-\frac{r}{a}} dr \right) \right) \Big|_0^\infty$$

$$u = r^2 \quad du = 2r dr \quad v = r \quad dv = dr \quad = 4\pi \rho_0 \left(r^2 a e^{-\frac{r}{a}} - 2a^2 r e^{-\frac{r}{a}} + 2a^3 e^{-\frac{r}{a}} \right) \Big|_0^\infty =$$

$$dv = e^{-\frac{r}{a}} dr \quad v = -a e^{-\frac{r}{a}} \quad dv = e^{-\frac{r}{a}} \quad v = -a e^{-\frac{r}{a}} \quad = 4\pi \rho_0 a \left(r^2 + 2ar + 2a^2 \right) \Big|_0^\infty =$$

$$= 4\pi \rho_0 a \cdot 2a^2 = 8\pi \rho_0 a^3$$

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b) $\oint_S \vec{E} \cdot \hat{n} dS = \frac{q_{int}}{\epsilon_0}$

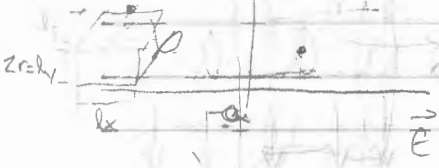
$E \cdot 4\pi r^2 = -\frac{4\pi \rho_0 a^3}{\epsilon_0} e^{-\frac{r}{a}} (r^2 + 2ar + 2a^2)$

$E r^2 = 2\rho_0 a^3 = \rho_0 a e^{-\frac{r}{a}} (r^2 + 2ar + 2a^2)$

$E = \frac{2\rho_0 a^3}{\epsilon_0 r^2} = \frac{\rho_0 a e^{-\frac{r}{a}}}{\epsilon_0} (1 + \frac{2a}{r} + \frac{2a^2}{r^2})$

$E = \frac{2\rho_0 a^3}{\epsilon_0 r^2} \left[1 - \frac{1}{2} e^{-\frac{r}{a}} \left(\frac{r^2}{a^2} + \frac{2r}{a} + 2 \right) \right]$

(14) $\oint_S \vec{E} \cdot \hat{n} dS = \frac{q}{\epsilon_0}$



$E \cdot 2lxz = 2alxz \cdot \rho$

$E = \frac{\rho l}{\epsilon_0} \hat{z} = E_{cima} = E_{baixo}$

$E \cdot 2lxz = \rho l x \cdot 2z$

$E_{meio} = \frac{\rho z}{\epsilon_0} \hat{z}$

b) $\text{div } E = \frac{\rho}{\epsilon_0}$

Meio:

Cima e baixo:

$\text{div } E = \frac{\rho}{\epsilon_0}$

$\text{div } E = 0 = \frac{\rho}{\epsilon_0}$

(15)

$\vec{E} = \vec{E}_{inf} - \vec{E}_b$

$E_{inf} \cdot 4\pi a^2 = \frac{4\pi \rho a^3}{\epsilon_0} = \frac{\rho a}{3\epsilon_0}$

$\vec{E} = \frac{\rho a}{3\epsilon_0} - \frac{\rho b}{3\epsilon_0} = \frac{\rho}{3\epsilon_0} (a-b) \hat{e}_b$

$\vec{E} = \frac{\rho}{3\epsilon_0} \vec{d} = d \hat{e}$

$\vec{d} = \vec{a} - \vec{b}$

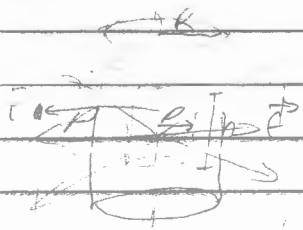


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interno

$$\oint_S \vec{E} \cdot d\vec{S} = \frac{q_{int}}{\epsilon_0}$$



$$E \cdot 2\pi r h = \frac{\pi r^2 h \delta}{\epsilon_0}$$

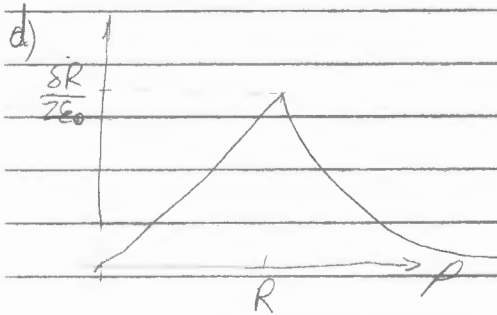
$$\vec{E} = \frac{\delta}{2\epsilon_0} \vec{\rho}$$

externo:

$$E \cdot 2\pi R h = \frac{\pi R^2 h \delta}{\epsilon_0}$$

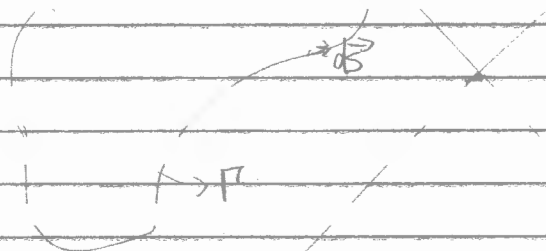
$$\vec{E} = \frac{\delta R}{2\epsilon_0} \hat{\rho}$$

b) $0 < \rho < R \Rightarrow |\vec{E}| = \frac{\delta \rho}{2\epsilon_0}$



c) $\oint \vec{E} \cdot d\vec{l} = 0$

$$\oint_{\Gamma} \vec{c} \cdot d\vec{s}$$



$$\oint_{\Gamma} \vec{c} \cdot d\vec{s} = \int_A (\nabla \times \vec{c}) \cdot \hat{n} dA$$

$$\nabla \times \vec{E} = 0$$